

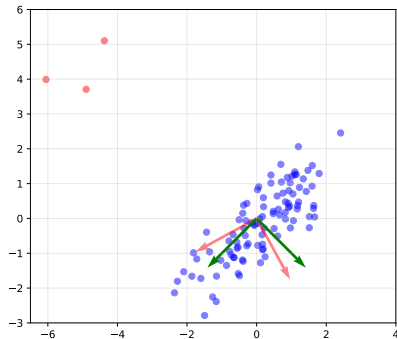
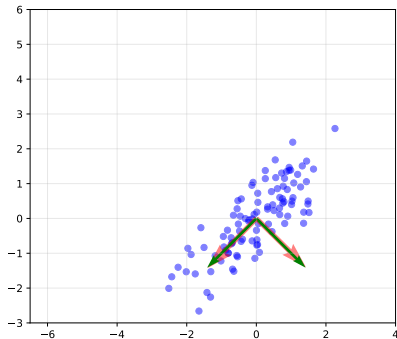
Tyler's M-estimator Through the Lens Of Convex-Concave Programming

Daniel Cederberg

Stanford University

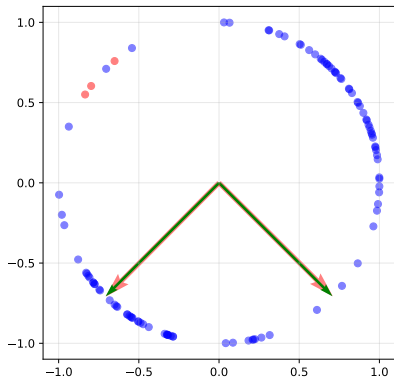
May 2, 2026

Robust covariance estimation



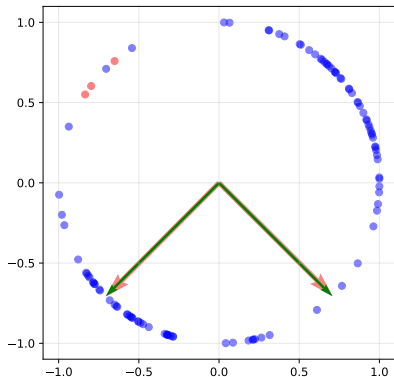
- ▶ classical covariance estimators are sensitive to outliers (red points)
- ▶ green arrows = true principal components, red = sample principal components

Angular central Gaussian distribution



- ▶ normalize samples to the unit sphere: $X \triangleq Z/\|Z\|_2$ where $Z \sim N(0, \Sigma)$
- ▶ outliers can only influence direction, not magnitude

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- ▶ outliers can only influence direction, not magnitude
- ▶ density of X is *angular central Gaussian* (ACG):

$$p(x; \Sigma) = \frac{\Gamma(n/2)}{2\pi^{n/2}\sqrt{\det \Sigma}} (x^T \Sigma^{-1} x)^{-n/2}$$

Tyler's M-estimator (Tyler, 1987)

A distribution-free M-estimator of multivariate scatter

DE Tyler - The annals of Statistics, 1987 - JSTOR

The existence and uniqueness of a limiting form of a Huber-type M-estimator of multivariate scatter is established under certain conditions on the observed sample. These conditions ...

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$$\text{minimize } \log \det \Sigma + \frac{n}{m} \sum_{i=1}^m \log(x_i^T \Sigma^{-1} x_i)$$

- ▶ variable $\Sigma \in \mathbf{S}^n$, data $x_1, \dots, x_m \in \mathbf{R}^n$
- ▶ MLE for the angular central Gaussian distribution
- ▶ well-known in the statistics literature (industry adoption is another story?)
- ▶ computed via fixed-point iteration:

$$\Sigma_{k+1} = \frac{n}{m} \sum_{i=1}^m \frac{x_i x_i^T}{x_i^T \Sigma_k^{-1} x_i}$$

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 - key idea: reinterpret fixed-point iteration as the convex-concave procedure
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 - key idea: reinterpret fixed-point iteration as the convex-concave procedure
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- ▶ come by my poster if you like covariance matrices, convergence rates (or CVXPY)