

Parameter-Free Dynamic Regret for Unconstrained Linear Bandits

Alberto Rumi* Andrew Jacobsen*

Nicolò Cesa-Bianchi Fabio Vitale

AISTATS 2026

Intesa Sanpaolo AI Research · Università degli Studi di Milano

Unconstrained linear bandits, dynamic comparator

The game. For $t = 1, \dots, T$:

- Learner plays $\mathbf{w}_t \in \mathbb{R}^d$ (unconstrained)
- Adversary picks loss vector $\ell_t \in \mathbb{R}^d$
- Learner observes only $\langle \ell_t, \mathbf{w}_t \rangle$ (bandit feedback)

Dynamic regret against an arbitrary sequence $\mathbf{u}_1, \dots, \mathbf{u}_T$:

$$R_T(\mathbf{u}_1, \dots, \mathbf{u}_T) = \sum_{t=1}^T \langle \ell_t, \mathbf{w}_t - \mathbf{u}_t \rangle.$$

Complexity of the comparator — number of switches:

$$S_T = \sum_{t=2}^T \mathbb{I}\{\mathbf{u}_t \neq \mathbf{u}_{t-1}\}.$$

The open problem

Lower bound: $\Omega\left(\sqrt{d(1 + S_T)T}\right)$.

Existing bandit algorithms achieve $\mathcal{O}\left(\sqrt{d(1 + S_T)T}\right)$ **only when S_T is given as input.**

Objective: Parameter-free: hit the optimal rate **without prior knowledge of S_T .**

- Full-information setting: solved. (Cutkosky '19, Zhang et al. '18, ...)
- Bandit setting: **open since Auer et al. 2002.**

Theorem (informal)

For any oblivious comparator sequence $\mathbf{u}_1, \dots, \mathbf{u}_T$,

$$\mathbb{E}[R_T(\mathbf{u}_1, \dots, \mathbf{u}_T)] = \tilde{O}\left(M\sqrt{d(1+S_T)T}\right),$$

where $M = \max_t \|\mathbf{u}_t\|$, with no prior knowledge of S_T or M .

- First optimal parameter-free dynamic regret for adversarial linear bandits.
- Resolves the long-standing open problem for **unconstrained linear bandits**.

Starting point: Cutkosky's iterate-adding trick

Full-info OCO (Cutkosky, 2019). Given N comparator-adaptive algos $\mathcal{A}_1, \dots, \mathcal{A}_N$:

$$\text{play } \mathbf{w}_t = \sum_{i=1}^N \mathbf{w}_t^{(i)} \implies R_T(\mathbf{u}) \leq \min_i R_T^{\mathcal{A}_i}(\mathbf{u}) + \mathcal{O}(N).$$

Iterate-adding — simple, competitive with the best base algorithm.

Breaks under bandit feedback. We only observe the scalar

$$\langle \ell_t, \sum_i \mathbf{w}_t^{(i)} \rangle.$$

We don't observe each learner's contribution \implies no proper feedback to individual \mathcal{A}_i 's.

The fix: uniform sampling

Instead of *summing* iterates, **sample one**:

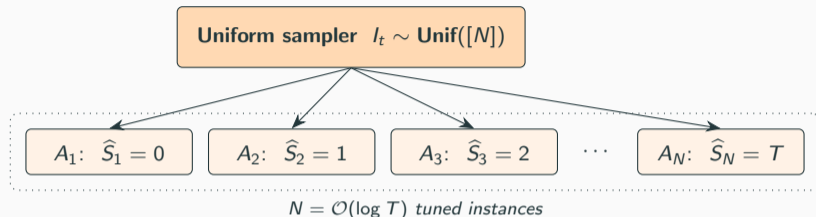
$$I_t \sim \text{Unif}([N]), \quad \mathbf{w}_t = \mathbf{w}_t^{(I_t)}.$$

In expectation this plays the *average*:

$$\mathbb{E}[\mathbf{w}_t] = \frac{1}{N} \sum_{i=1}^N \mathbf{w}_t^{(i)}.$$

Cost. Comparator *rescaled* by N .

Uniform Sampling in practice



Base algo $\Rightarrow \mathcal{A}_i$ that guarantees $\tilde{\mathcal{O}}(\sqrt{d(1 + S_T)T})$ when given S_T .

(Luo et al. '22 + van der Hoeven et al. '20)

Guess on a geometric grid

$$\hat{S} \in \{0, 1, 2, 4, 8, \dots, T\}, \quad N = \mathcal{O}(\log T) \text{ guesses}$$

Some \hat{S}_n always satisfies $\hat{S}_n \leq S_T \leq 2\hat{S}_n$.

Uniform sampling \Rightarrow inherit the best instance's guarantee, up to log factors.

Takeaways

- **First** $\tilde{O}(\sqrt{d(1 + S_T)T})$ **parameter-free dynamic regret** for unconstrained linear bandits.
- **Tool:** uniform sampling — a bandit-friendly replacement for iterate-adding.
- **Next Questions?**
 - Fully adaptive adversary (over comparators too)?
 - Path-length P_T instead of switches S_T ?
 - Constrained domains?

Come at poster #174!