

# Panprediction

Optimal Predictions for Any Downstream Task and Loss

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(Berkeley)

Optimal Predictions for *Any* Downstream Task and Loss

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**Isn't this a calibration session?**

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- Binary labels  $Y \in \{0,1\}$
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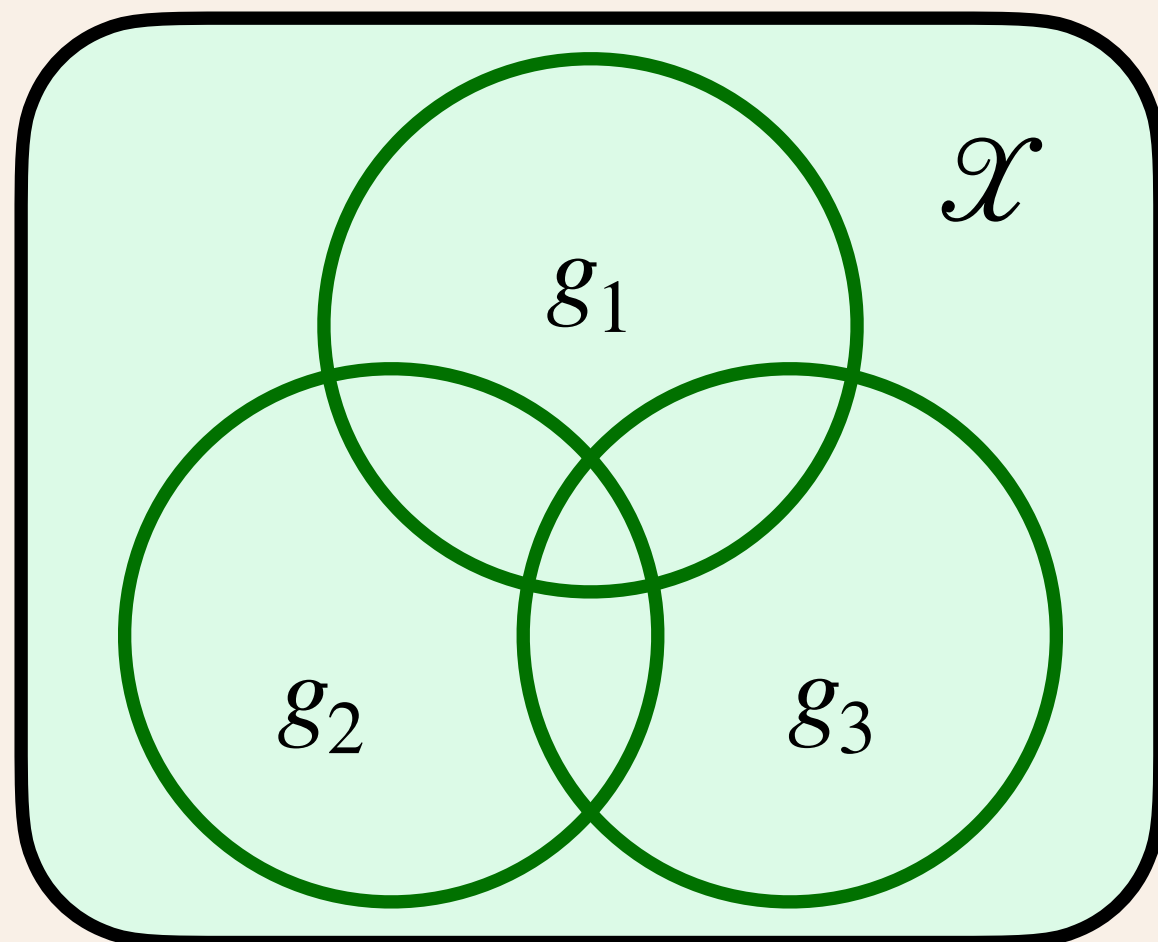
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Groups  
 $\mathcal{G} \subseteq 2^{\mathcal{X}}$



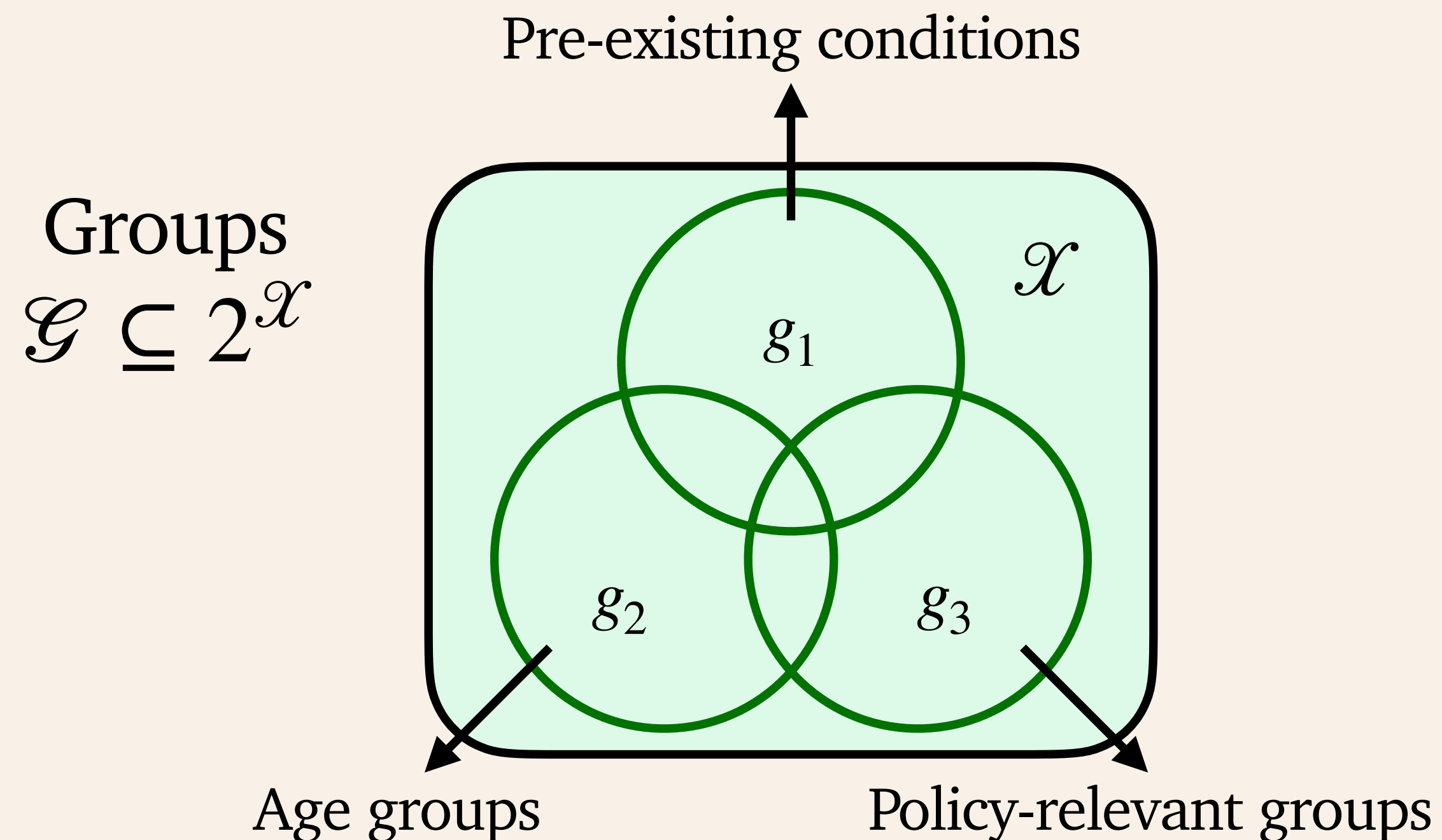
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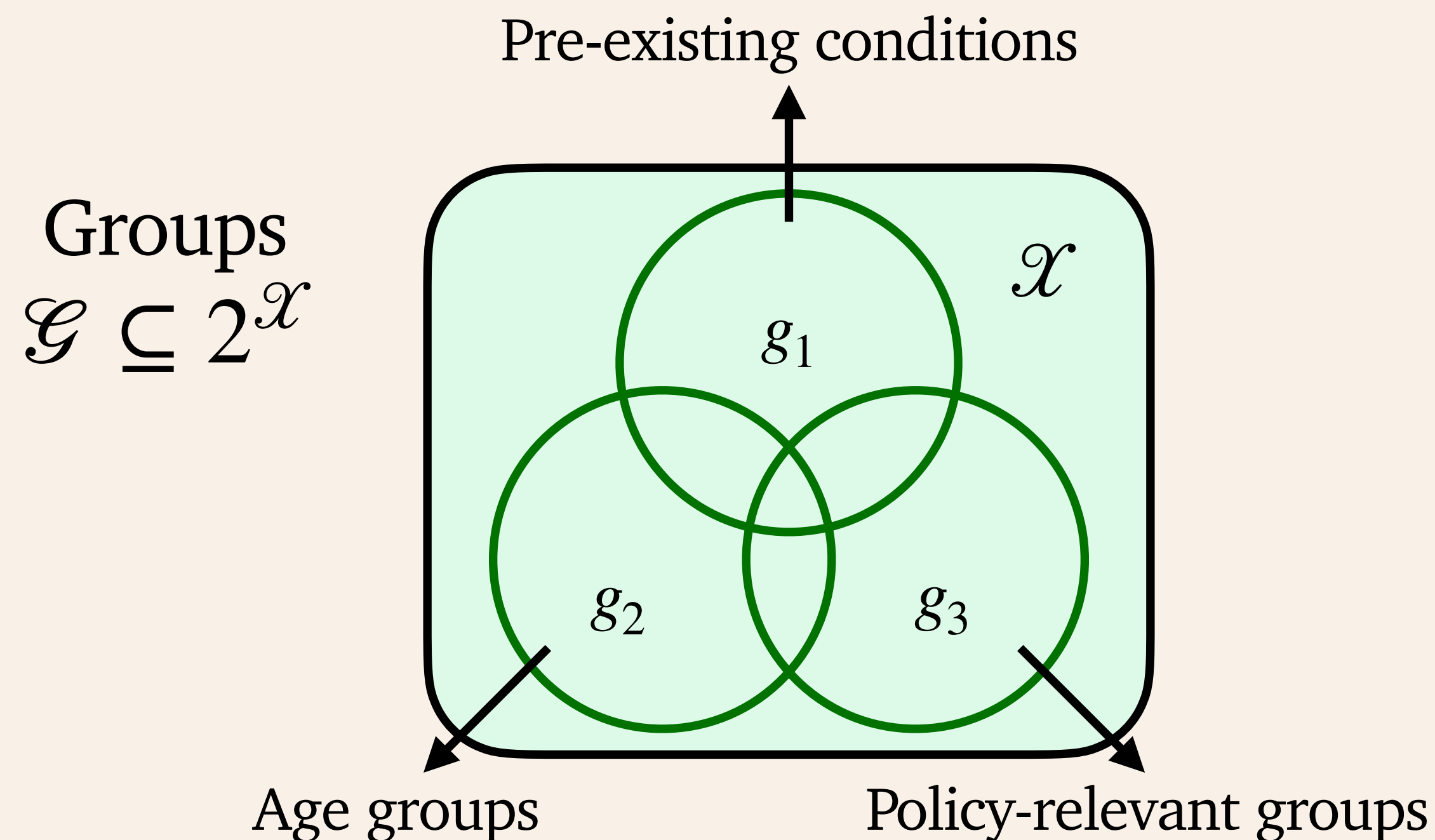
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If  $X$  is in group  $g \in \mathcal{G}$ , say  $g(X) = 1$

A task induced by  $g$  is the group-conditional distribution  $D_g = D \mid_{g(X)=1}$

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$(\ell_1, g_1)$

**Discharge  
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$(\ell_2, g_2)$

**Actuary**

$(\ell_3, g_3)$

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$$h_1 = \arg \min_{h \in \mathcal{H}} \mathbb{E}_{(X,Y) \sim D_{g_1}} [\ell_1(h(X), Y)]$$

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$$h_2 = \arg \min_{h \in \mathcal{H}} \mathbb{E}_{(X,Y) \sim D_{g_2}} [\ell_2(h(X), Y)]$$

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Want our model to compete with  $h_1, h_2, h_3$  simultaneously

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Say our model  $\hat{h}$  is  **$\varepsilon$ -optimal with respect to  $\mathcal{H}$**  if for every group  $g \in \mathcal{G} = \{g_1, g_2, g_3\}$  and loss  $\ell \in \mathcal{L} = \{\ell_1, \ell_2, \ell_3\}$ ,

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We only know  
 $(\mathcal{L}, \mathcal{G}, \mathcal{H})$

Competitor adapts  
to  $\ell$  and  $g$

# Upstream vs Downstream

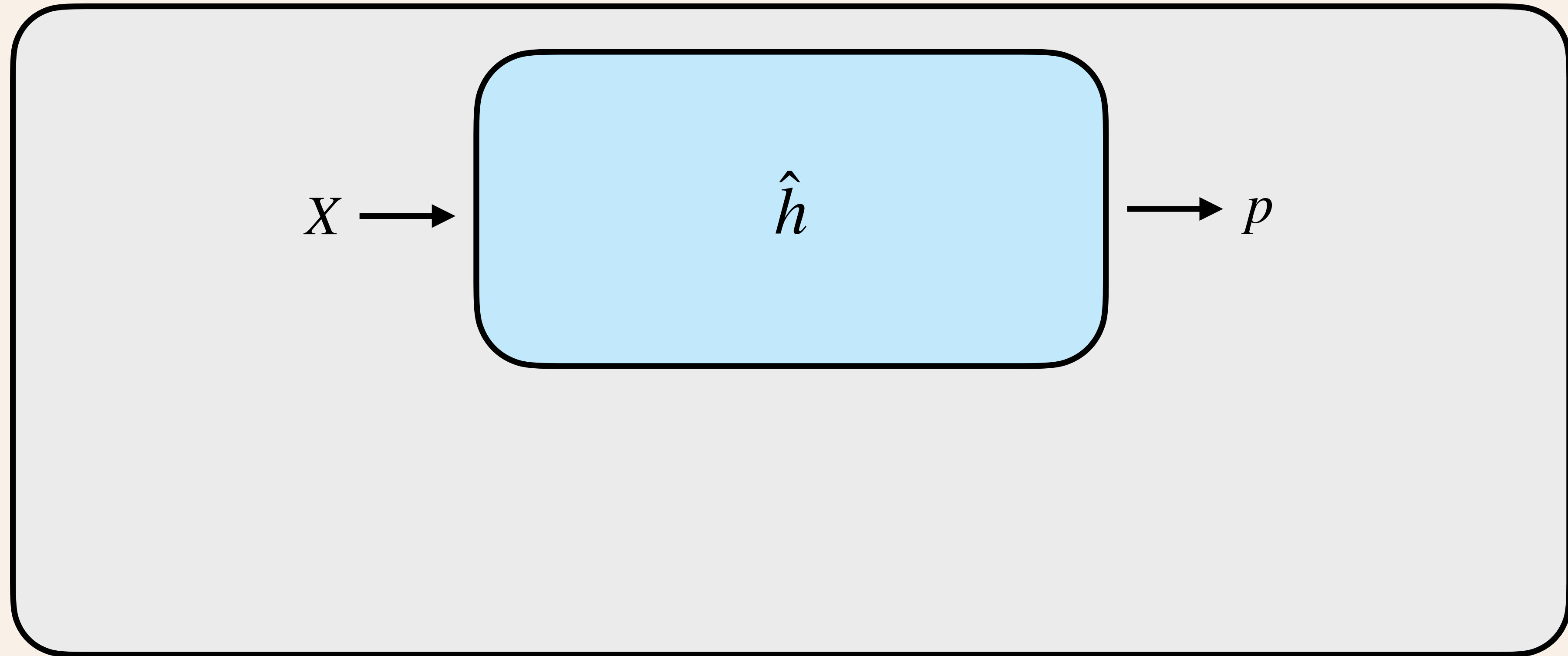
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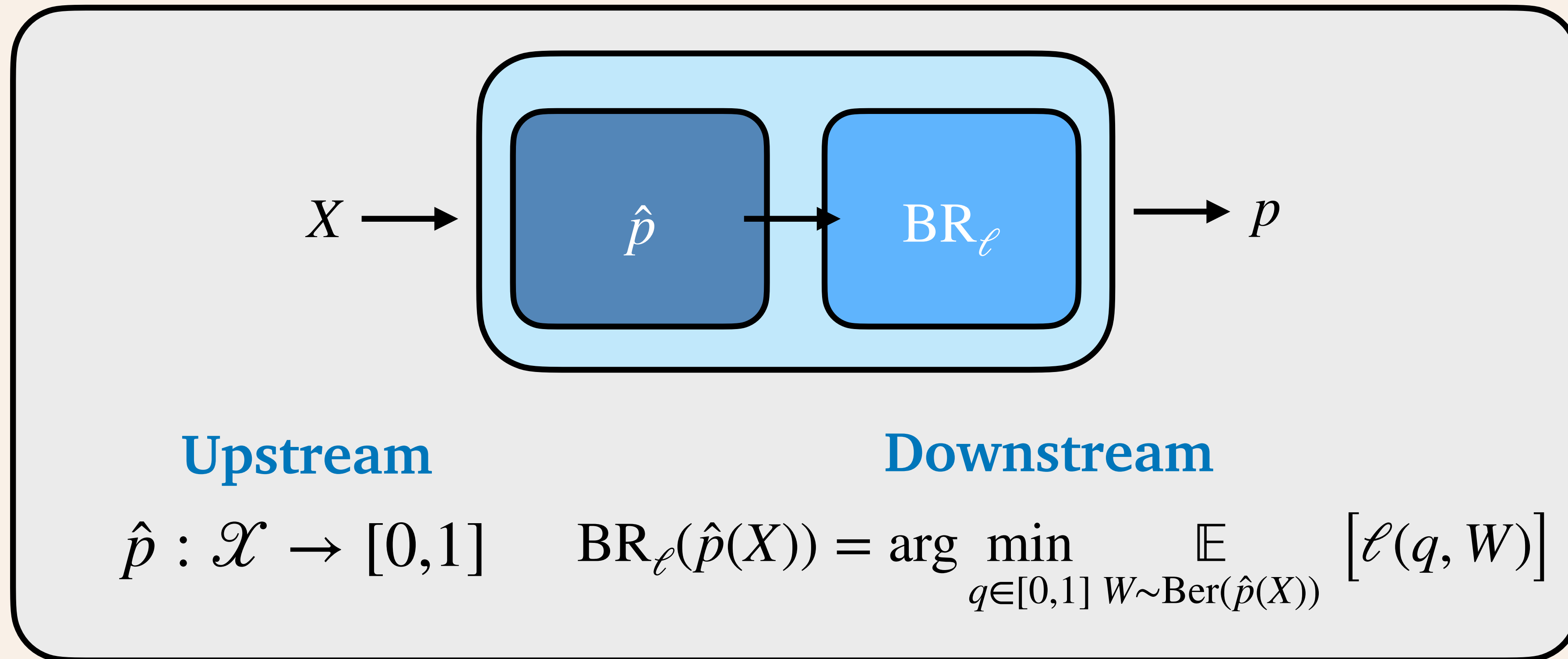
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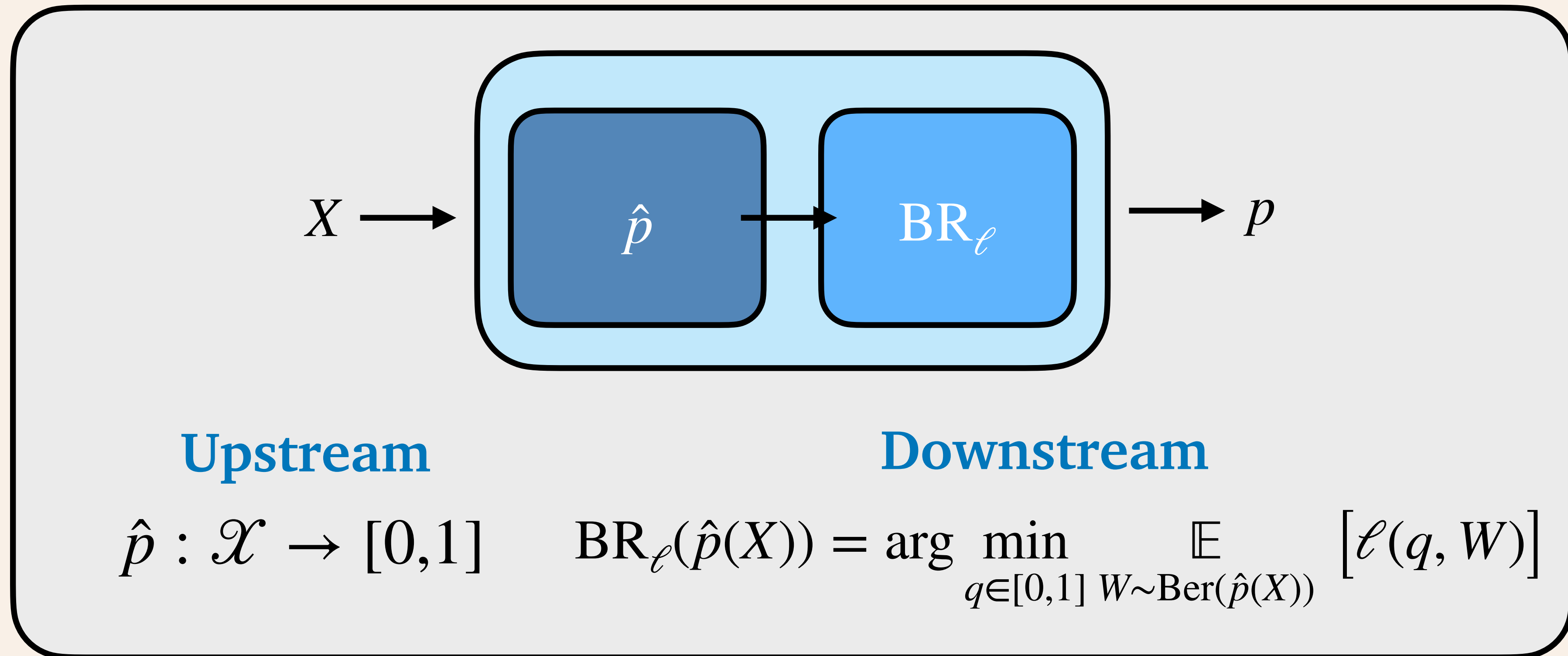
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For each loss  $\ell \in \mathcal{L}$ , we have  $\hat{h}_\ell = \text{BR}_\ell \circ \hat{p}$ . But only  $\hat{p}$  needs to be **learned**.

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Learn a predictor  $\hat{p} : \mathcal{X} \rightarrow [0,1]$  such that for all  $g \in \mathcal{G}$  and  $\ell \in \mathcal{L}$ ,

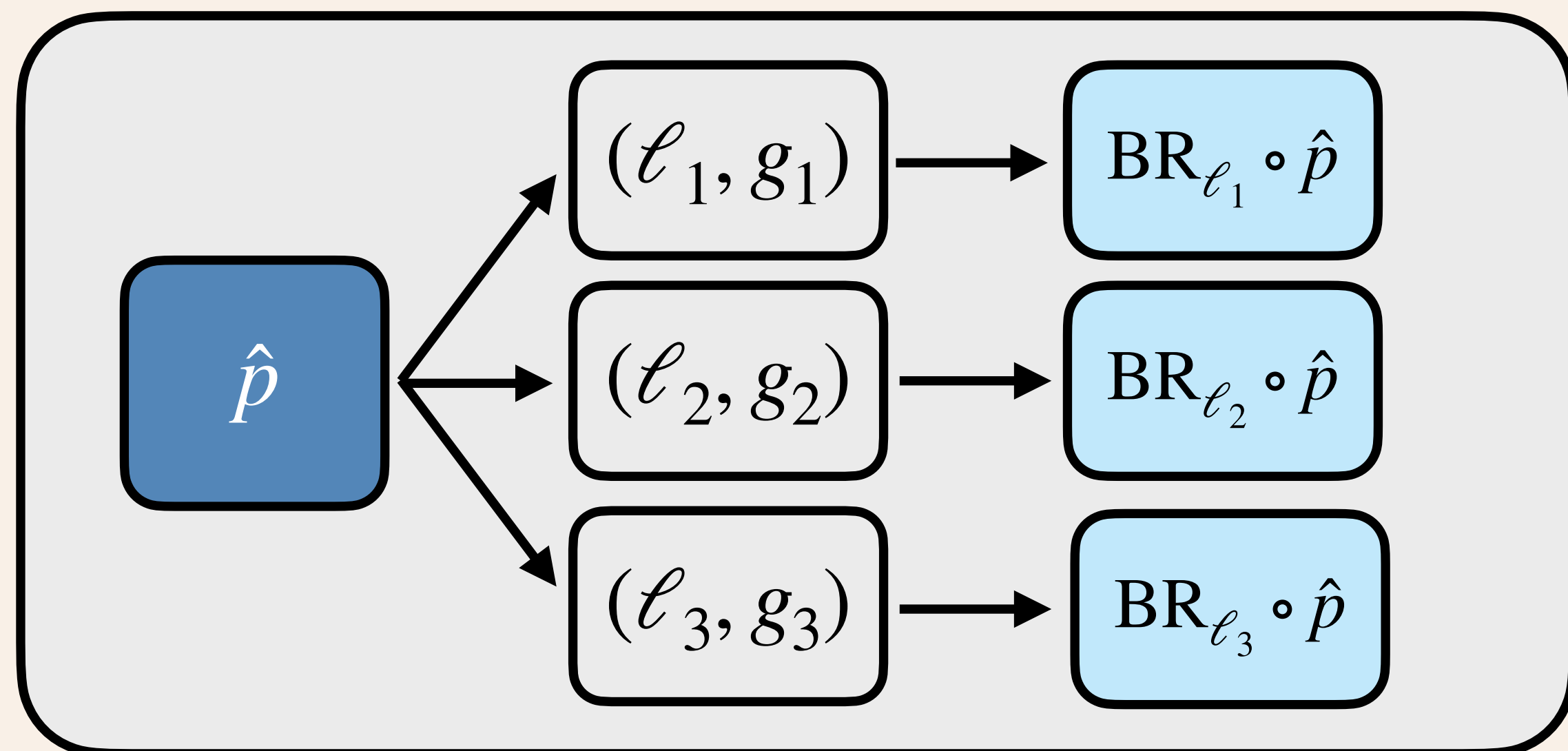
$$\mathbb{E}_{(X,Y) \sim D_g} \left[ \ell((\text{BR}_\ell \circ \hat{p})(X), Y) \right] \approx_\varepsilon \min_{h \in H} \mathbb{E}_{(X,Y) \sim D_g} \left[ \ell(h(X), Y) \right].$$

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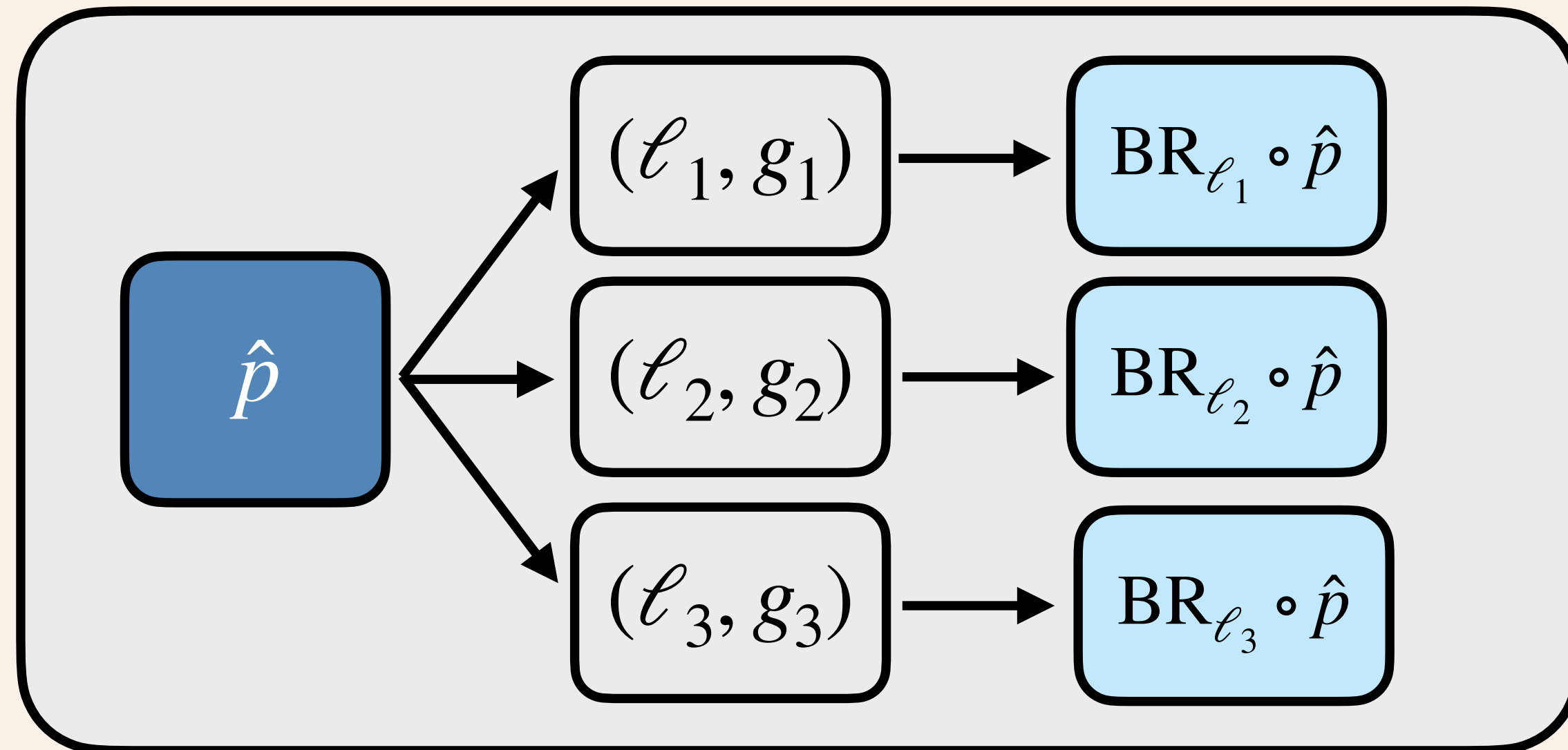


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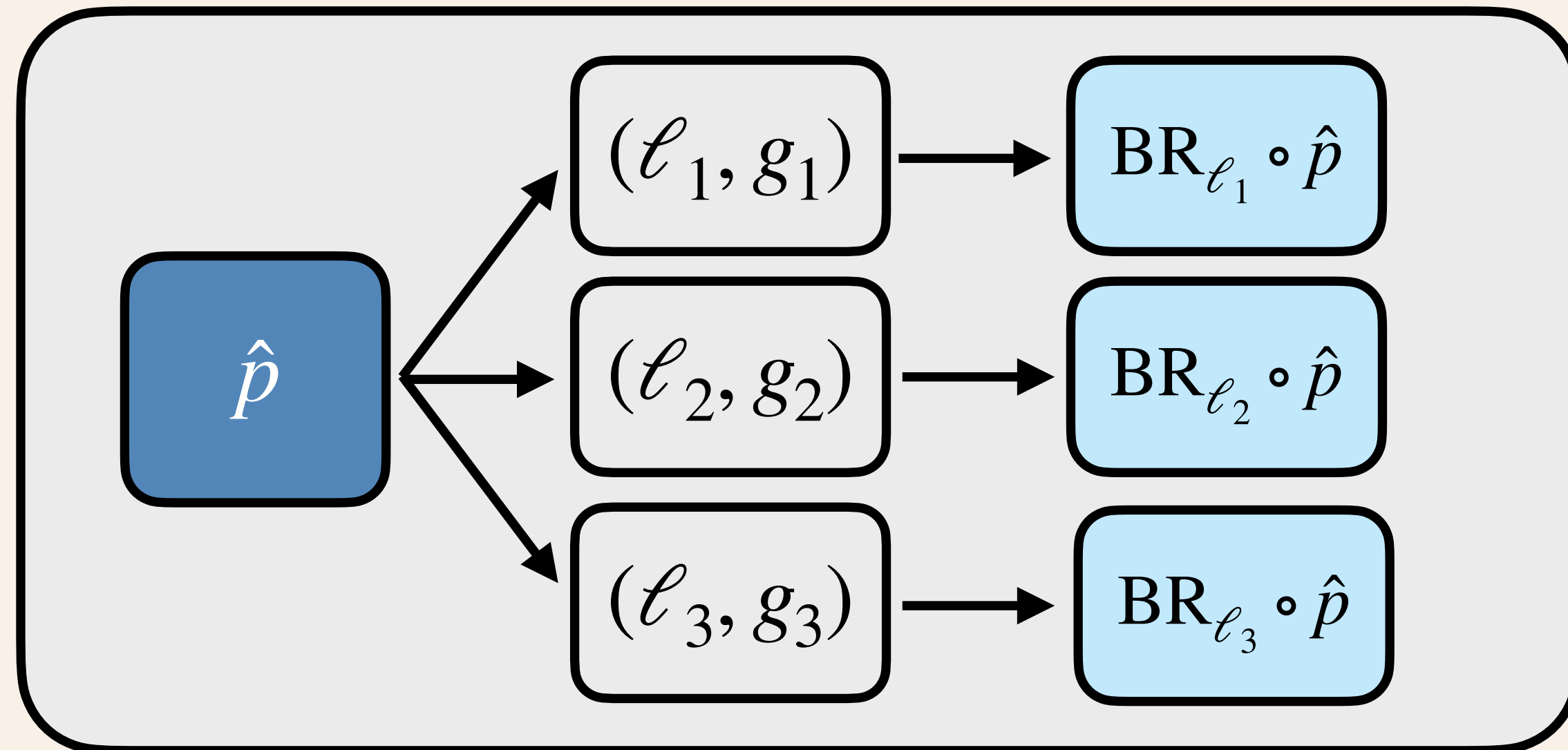
**Non-vacuous! Bayes predictor**  
 $p^\star(x) = \mathbb{P}_{(X,Y) \sim D}(Y = 1 \mid X = x)$   
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Suffices to learn a **coarsening** of  $p^\star$

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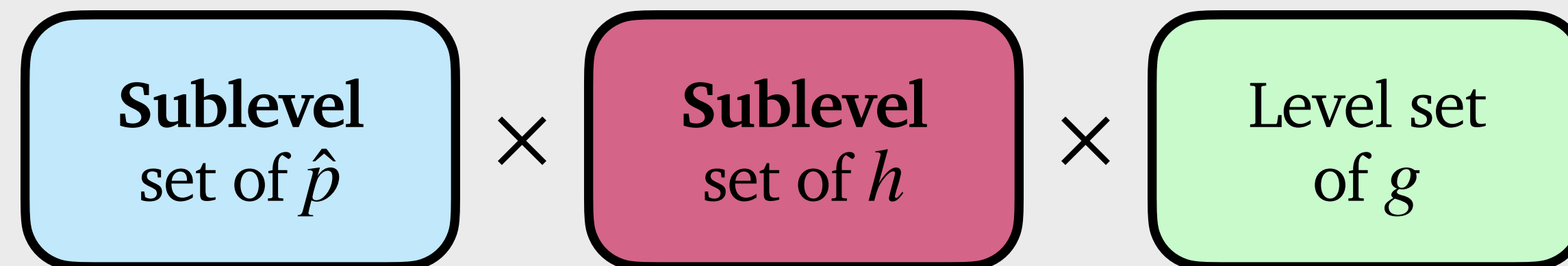
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Predictions are **unbiased** over all sets of the form



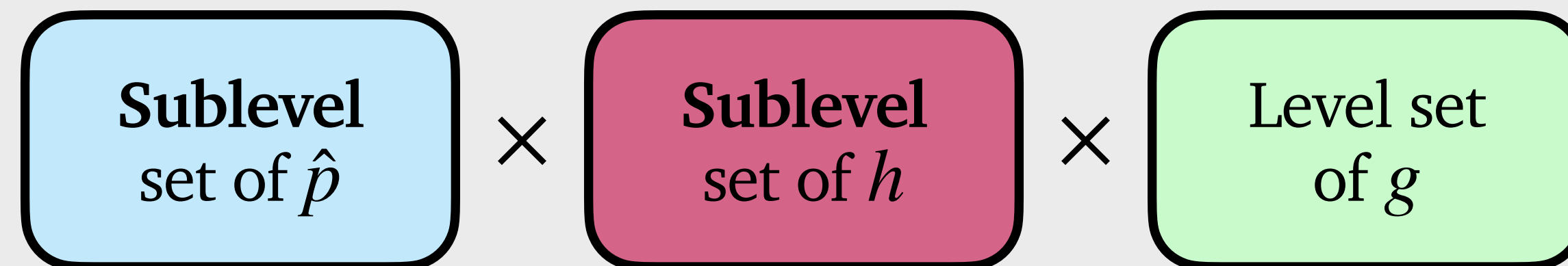
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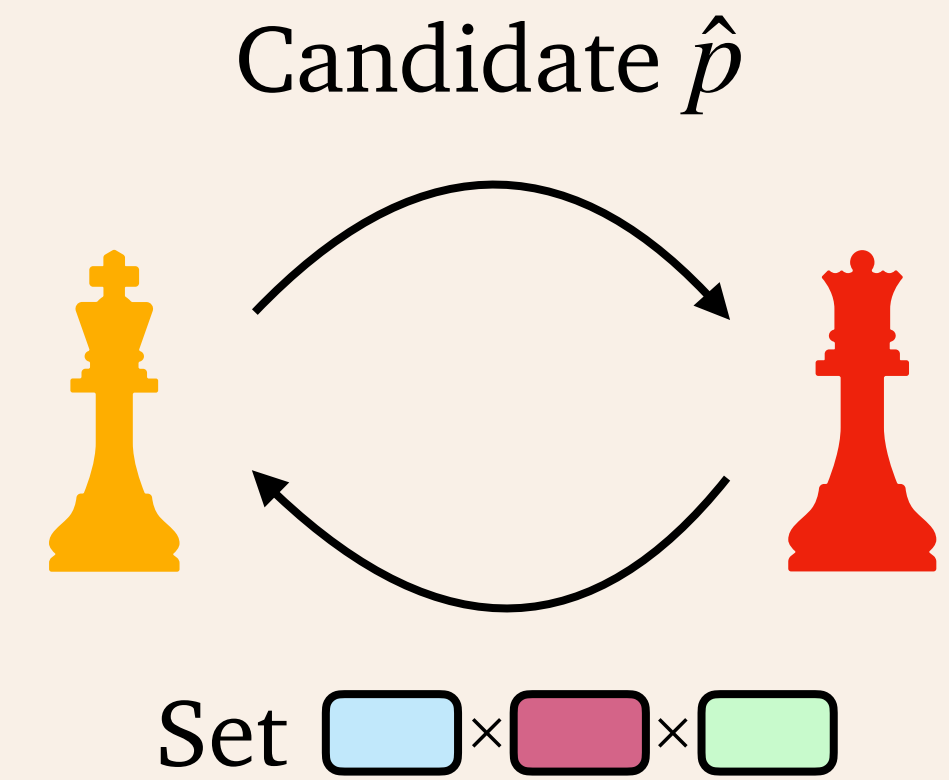


(Cf. multicalibration, which asks for unbiasedness on products of level sets ... **inefficient**)

# Algorithms

Based on **no-regret learning dynamics**

- Primal player: construct candidate panpredictor  $\hat{p}$
- Dual player: identify set with large calibration error



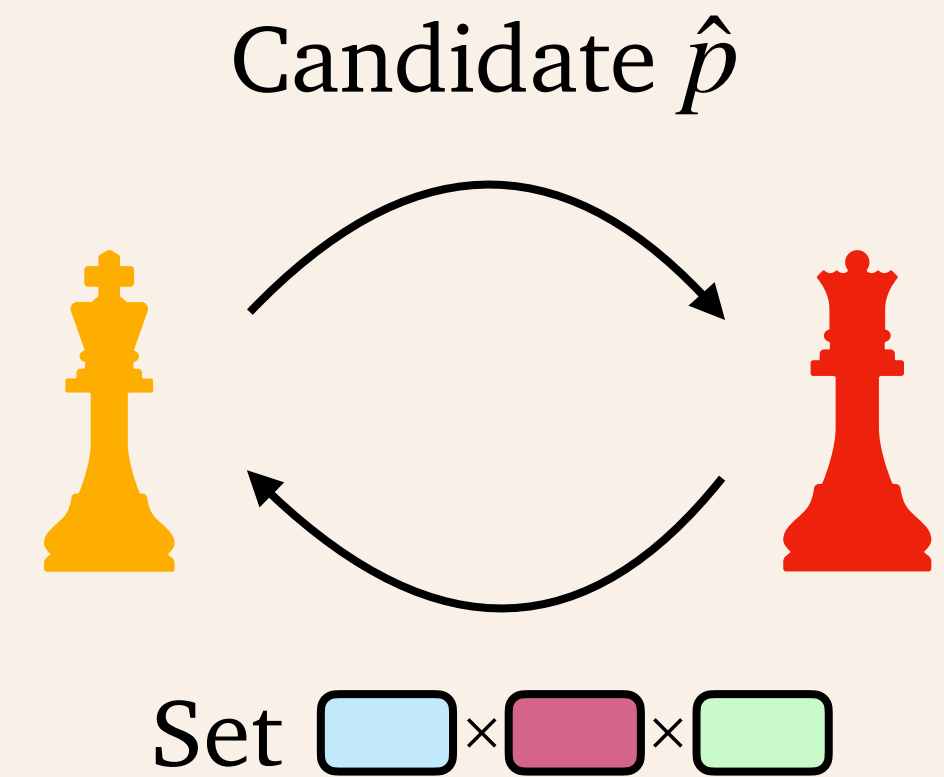
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Optimizing **many losses** over **many tasks** can be as **statistically easy** as optimizing one loss over one task, thanks to a reduction to **step calibration**.

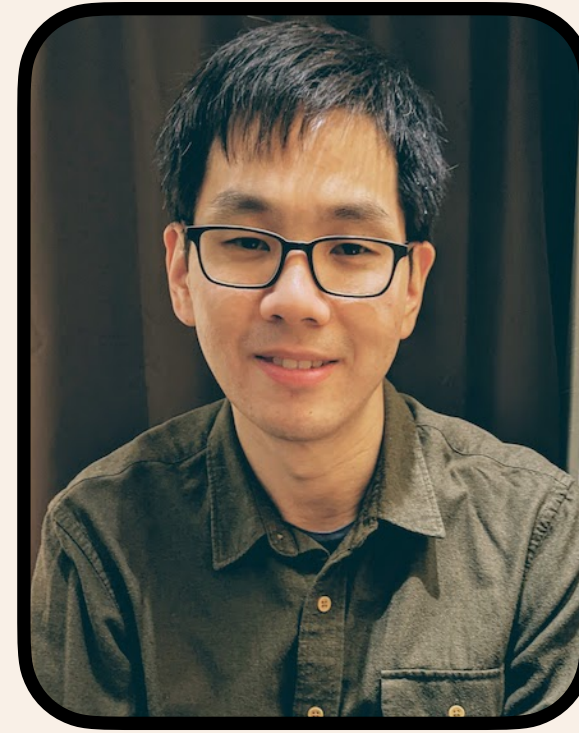
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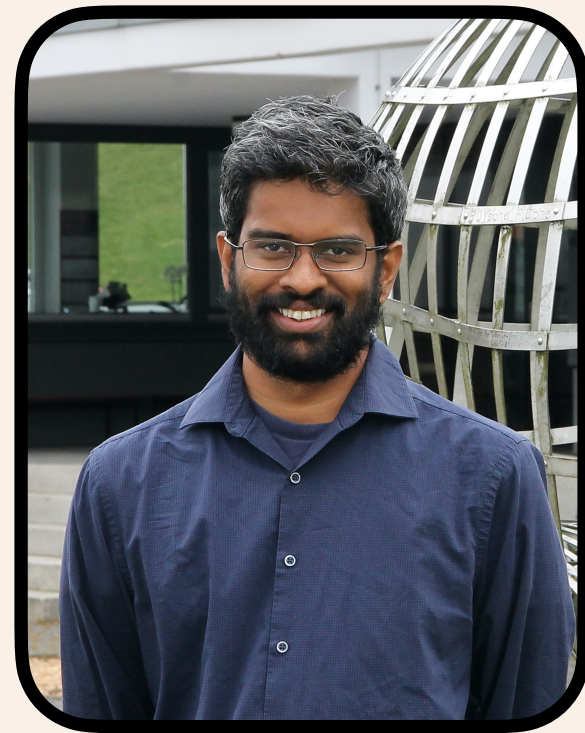


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- [QZ25] Qiao and Zhao. Truthfulness of Decision-theoretic Calibration Measures. 2025.
- [GKR+22] Gopalan et al. Omnipredictors. 2022.
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- [HJZ23] Haghtalab, Jordan, Zhao. Unifying View of Multicalibration. 2023.

**Calibration Workshop**  
on 05/05

# Thanks!



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## References

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