

Learning Laplacian Positional Encodings



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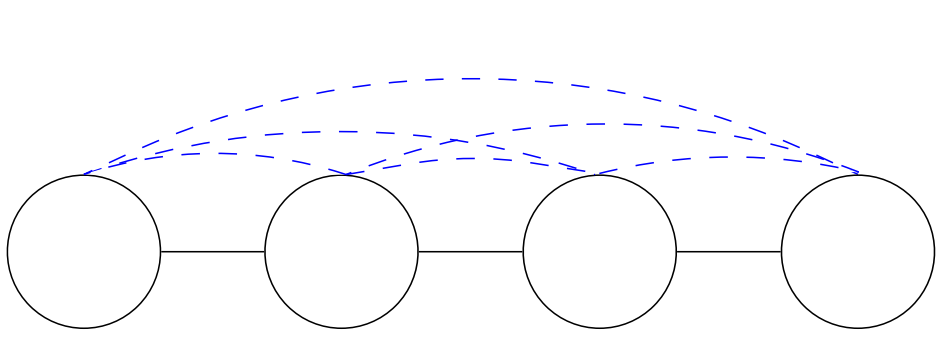
1. Motivation

Transformers have led to tremendous progress in NLP and CV. How can we design transformers *for arbitrary graphs*?

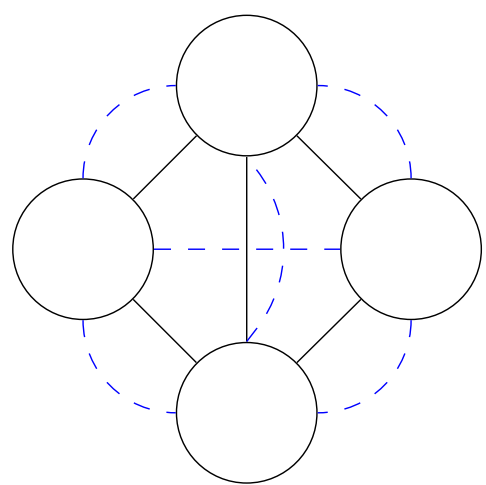
Laplacian PEs, the **first k** eigenvectors of the Laplacian, *generalize* sin/cos to graphs

$$L = D - A \rightarrow L = U^\top \Lambda U, \quad P = U[:, : k]$$

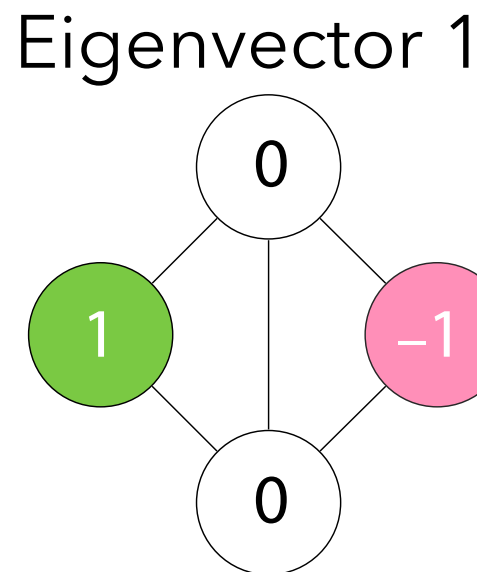
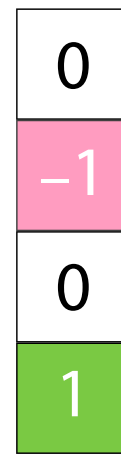
Sinusoidal PEs



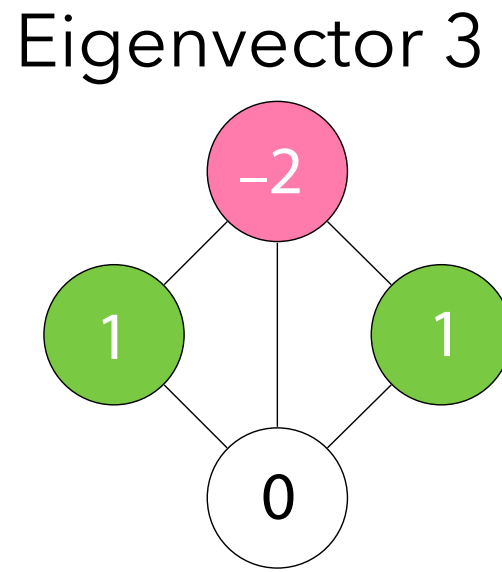
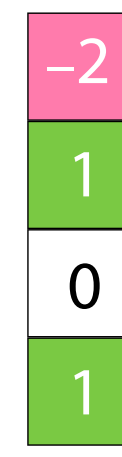
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\mathbf{u}_1

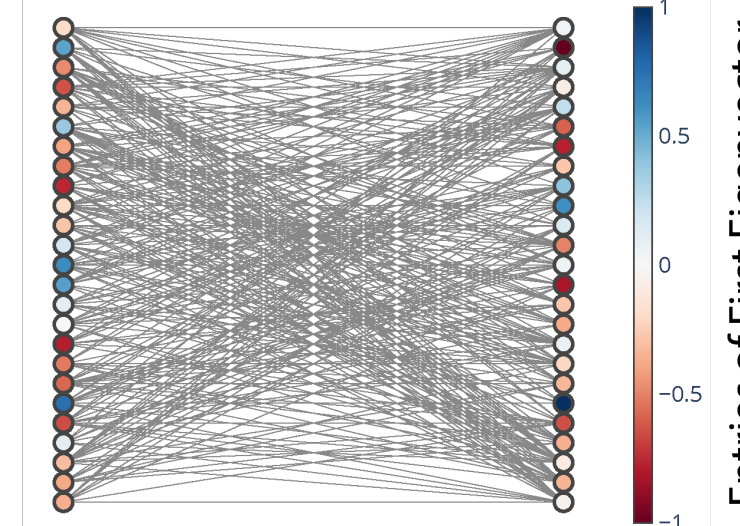


$\dots \mathbf{u}_3$

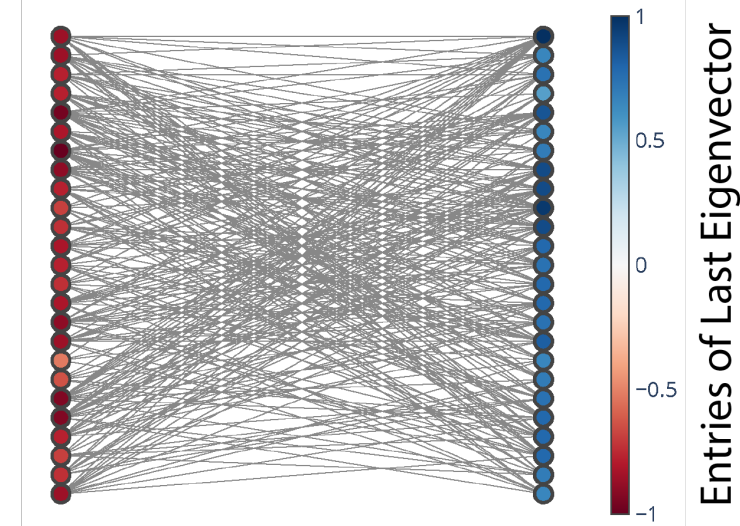


While LPEs are beneficial for **homophilous graphs**, we show they are not beneficial for **heterophilous graphs**.

First Eigenvector of Heterophilous SBM



Last Eigenvector of Heterophilous SBM



2. Learnable Laplacian PEs (LLPEs)

Intuition for learning LPEs: Leverage the **full** eigenvector matrix \mathbf{U} along with their corresponding eigenvalues Λ

We learn mapping $h: [0, 2] \rightarrow \mathbb{R}$ where $h(\lambda_i)$ is eigenvector i 's importance

$$\mathbf{P}_{\text{LLPE}} = \mathbf{U} \mathbf{W}_{\text{LLPE}}, \quad \mathbf{W}_{\text{LLPE}} = \begin{pmatrix} h(\lambda_0; \boldsymbol{\theta}_0) & \cdots & h(\lambda_0; \boldsymbol{\theta}_d) \\ \vdots & \ddots & \vdots \\ h(\lambda_n; \boldsymbol{\theta}_0) & \cdots & h(\lambda_n; \boldsymbol{\theta}_d) \end{pmatrix},$$

where $\boldsymbol{\theta}_j$ parametrizes h . We then set h as a truncated **Chebyshev series**,

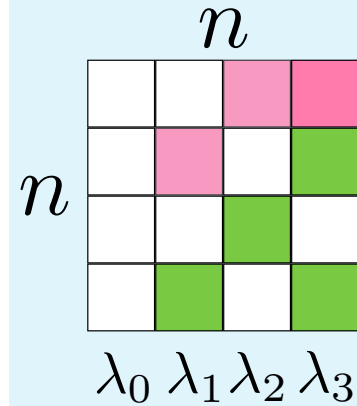
$$h(\lambda_i; \boldsymbol{\theta}_j) = \sum_{m=0}^M \boldsymbol{\theta}_j[m] \cdot T_m(\tilde{\lambda}_i), \quad T_m(\tilde{\lambda}_i) = \cos(m \cdot \arccos(\tilde{\lambda}_i))$$

where $\boldsymbol{\theta}_j$ are learnable Chebyshev weights.

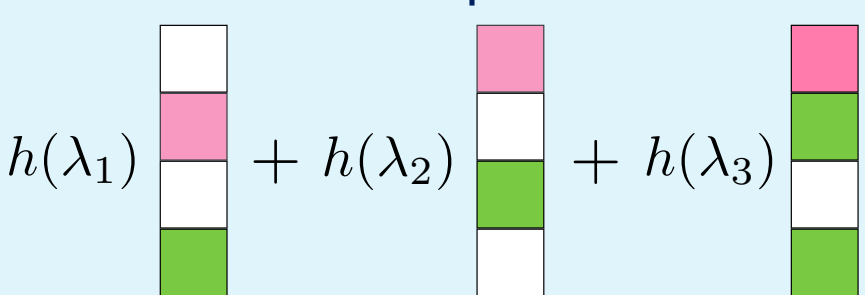
LLPEs Exhibit Tighter Generalization

LLPEs operate on the *significantly smaller* Laplacian spectrum, as opposed the *full* eigenspace

Other PEs



Learnable Laplacian PEs



LLPEs Can Approximate Graph Distances

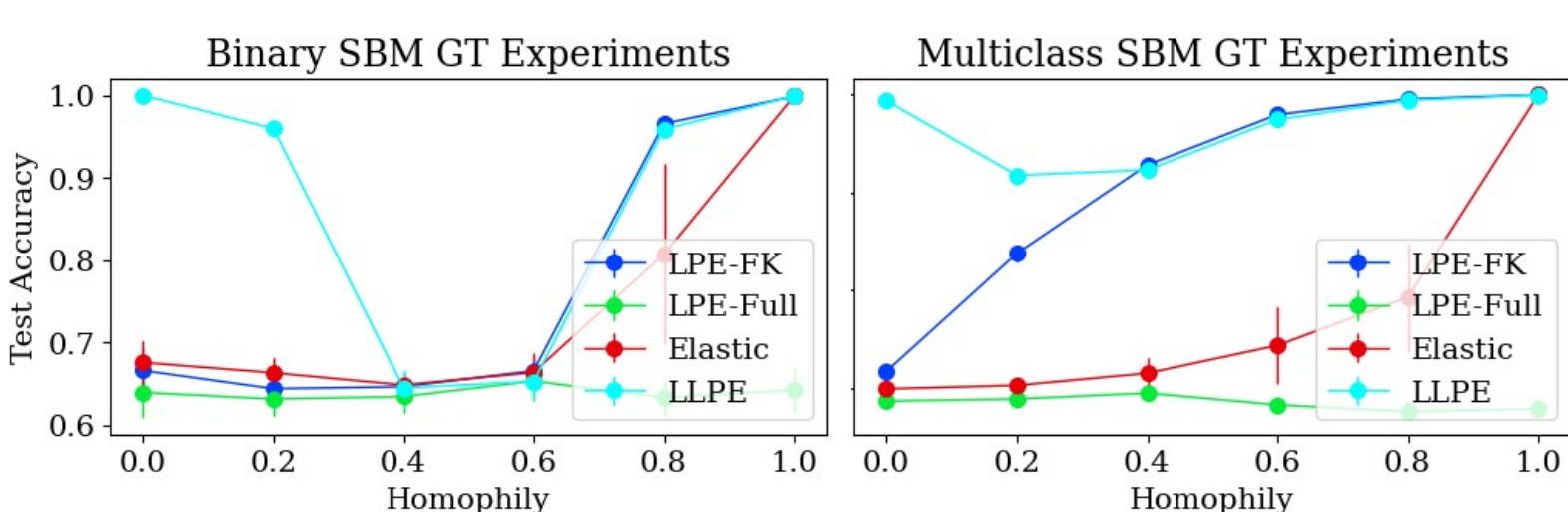
LLPE can approximate *distances on graphs*, including random walks, heat kernels, and diffusion --- formally, distances defined

$$f_r(i, j)^2 = \sum_{k=1}^n r(\lambda_k) (\mathbf{u}_k[i] - \mathbf{u}_k[j])^2.$$

where i and j are nodes and $r: [0, 2] \rightarrow \mathbb{R}^+$.

3. Experimental Results

LLPE identifies relevant graph structure on synthetic SBMs



	Tolokers	Cora-Full	Computers	Cora
# Nodes $ V $	11.7K	19.7K	13.7K	2.7K
# Edges $ E $	519K	126.8K	491.7K	5.4K
Homophily	0.17	0.50	0.70	0.75
ElasticPE	73.23 \pm 2.90	57.92 \pm 1.39	85.28 \pm 0.86	74.67 \pm 1.68
SAN-PE	78.42 \pm 1.15	60.25 \pm 0.60	85.36 \pm 0.55	73.16 \pm 1.40
SignNet	73.96 \pm 0.86	60.28 \pm 0.59	85.09 \pm 0.68	72.66 \pm 2.28
RWSE	74.09 \pm 0.69	60.07 \pm 0.87	85.05 \pm 0.83	74.27 \pm 2.28
LLPE (ours)	80.85 \pm 0.83	61.02 \pm 0.60	87.83 \pm 0.45	80.83 \pm 1.33

Across a range of homophily LLPEs outperform existing PEs on complex real graphs

We propose a **new learnable Laplacian position encoding** that helps capture graph structure in both homophilous and heterophilous settings by leveraging the **full spectrum of the graph Laplacian**, representing a significant step in developing data-driven PEs that capture complex graph structures