Absence of spurious solutions far from ground truth: A low-rank analysis with high-order losses

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We study the following low-rank matrix recovery problem:

$$\begin{split} \min_{X \in \mathbb{R}^{n \times r}} f(X) &\coloneqq \frac{1}{2} \|\mathcal{A}(XX^T) - b\|^2 \\ &= \frac{1}{2} \|\mathcal{A}(XX^T - ZZ^\top)\|^2 \end{split} \tag{1}$$

 $\blacktriangleright \mathcal{A}: \mathbb{R}^{n \times n} \to \mathbb{R}^m:$

$$\mathcal{A}(M) = [\langle A_1, M \rangle, \dots, \langle A_m, M \rangle]^T,$$

 $\blacktriangleright \ A_1, \ldots, A_m \in \mathbb{R}^{n \times n} \text{ are called sensing matrices. } b = \mathcal{A}(M^*).$

Definition 1

The linear operator $\mathcal{A}(\cdot):\mathbb{R}^{n\times n}\to\mathbb{R}^m$ is said to satisfy the $\delta\text{-RIP}_{2r}$ property for some constant $\delta\in[0,1)$ if the inequality

$$(1-\delta)\|M\|_F^2 \le \|\mathcal{A}(M)\|^2 \le (1+\delta)\|M\|_F^2$$

holds for all $M \in \mathbb{R}^{n \times n}$ with $\operatorname{rank}(M) \leq 2r$.

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- ▶ [Bhojanapalli et al., 2016] For factorized problem (1), as long as $\delta_{2r} \leq 1/5$, all second-order critical points (SOPs) of (1) are ground truth solutions.
- ▶ [Zhang et al., 2019] $\delta_{2r} = 1/2$ was a sharp bound when $r = r^*$, meaning that as long as $\delta_{2r} < 1/2$, all problem instances of (1) are free of spurious solutions, and once $\delta_{2r} \ge 1/2$, it is possible to establish counter-examples with SOPs not corresponding to ground truth solutions.

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- ▶ Over-parametrization with $r \ge r^*$. [Zhang, 2022] proved that if $r > r^*[(1 + \delta_n)/(1 \delta_n) 1]^2/4$, with $r^* \le r < n$, then every SOP \hat{X} satisfies that $\hat{X}\hat{X}^\top = M^*$.

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- ▶ The SDP approach. When using SDP, it was recently proven in [Yalcin et al., 2023] that as long as the RIP constant δ_{2r^*} is lower than the maximum of 1/2 and $2r^*/(n + (n 2r^*)(2l 5))$, the global solution of the SDP relaxation corresponds to M^* .

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 - 1. increase the complexity of the algorithm by a large margin (via over-parametrization $r \gg r^*$, SDP relaxation, or tensor optimization).
 - 2. initialize the algorithm close to M^* .
- Does there exist meaningful global guarantees for (1) in the case of $\delta \ge 1/2$ without increasing the computational complexity of the problem drastically?

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 \blacktriangleright We study the landscape far away from M^* in the problematic case $\delta_{2r} \geq 1/2.$

Lemma 2

A point X is a first-order critical point of (1) if

$$\nabla f(X) = \left(\sum_{i=1}^{m} \langle A_i, XX^{\top} - M^* \rangle A_i\right) X = 0$$
(2)

and it is a second-order critical point if it satisfies the above condition together with

$$\nabla^2 f(X)[U,U] = \sum_{i=1}^m \langle A_i, UX^\top + XU^\top \rangle^2 + \langle A_i, XX^\top - M^* \rangle \langle A_i, 2UU^\top \rangle \ge 0 \quad \forall U \in \mathbb{R}^n$$
(3)

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Theorem 3

Assume that (1) satisfies the RIP_{r+r^*} property with constant $\delta \in [0,1)$. Given a first-order critical point $\hat{X} \in \mathbb{R}^{n \times r}$ of (1), if it satisfies the inequality

$$\|\hat{X}\hat{X}^{\top} - M^*\|_F^2 > 2\frac{1+\delta}{1-\delta}\operatorname{tr}(M^*)\sigma_r(\hat{X})^2, \tag{4}$$

then \hat{X} is not a second-order critical point and is a strict saddle point with $\nabla^2 f(\hat{X})$ having a strictly negative eigenvalue not larger than

$$2(1+\delta)\sigma_r(\hat{X})^2 - \frac{\|\hat{X}\hat{X}^\top - M^*\|_F^2(1-\delta)}{\operatorname{tr}(M^*)}$$
(5)

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Theorem 4 ([Zhang and Zhang, 2020])

Assume that (1) satisfies the RIP property with constant $\delta \in [0, 1)$. Given an arbitrary constant $\tau \in (0, 1 - \delta^2)$, if a second-order critical point $\hat{X} \in \mathbb{R}^{n \times r}$ of (1) satisfies

$$\|\hat{X}\hat{X}^{\top} - M^*\|_F \le \tau \lambda_{r^*}(M^*)$$
(6)

then \hat{X} corresponds to the ground truth solution. Theorem 5

Consider the problem (1) under the RIP_{r+r^*} property with a constant $\delta \in [0,1)$. Assume that its ground truth solution M^* satisfies the following inequality

$$\|M^*\|_F \frac{\operatorname{tr}(M^*)}{\lambda_{r*}^2(M^*)} \le \frac{\sqrt{r}}{2\sqrt{2}} (1+\delta)^{1/2} (1-\delta)^{7/2}, \tag{7}$$

Then, every second-order critical point \hat{X} of (1) satisfies

$$\hat{X}\hat{X}^{\top} = M^*$$

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- Although Theorem 3 proves that critical points far away from the ground truth are strict saddle points, the time needed to escape such points depends on the local curvature of the function [Ge et al., 2017, Jin et al., 2021].
- Therefore, it is essential to understand whether the curvatures at saddle points could be enhanced to reshape the landscape favorably.
- In this work, we address this problem by the use of a modified loss function

$$\min_{X \in \mathbb{R}^{n \times r}} f^l_{\lambda}(X) \coloneqq f(X) + \lambda f^l(X)$$
(8)

where

$$f^{l}(X) \coloneqq \frac{1}{l} \|\mathcal{A}(XX^{\top}) - b\|_{l}^{l}$$
(9a)

$$h^{l}(M) := \frac{1}{l} \|\mathcal{A}(M) - b\|_{l}^{l}$$
(9b)

Theorem 6

Assume that the operator $\mathcal{A}(\cdot)$ satisfies the RIP_{r+r^*} property with constant $\delta \in [0, 1)$. Consider the high-order optimization problem (8) such that $l \geq 2$ is even. Given a first-order critical point $\hat{X} \in \mathbb{R}^{n \times r}$ of (8), if

$$D^{2} \ge \operatorname{tr}(M^{*})\sigma_{r}^{2}(\hat{X})\frac{(1+\delta)+\lambda(l-1)(1+\delta)^{l/2}D^{l-2}}{(1-\delta)/2+\lambda C(l)(1-\delta)^{l/2}D^{l-2}},$$
(10)

then \hat{X} is a strict saddle point with $\nabla^2 f(\hat{X})$ having a strictly negative eigenvalue not larger than

$$\begin{bmatrix} 2(1+\delta)\sigma_r(\hat{X})^2 - \frac{D^2(1-\delta)}{\operatorname{tr}(M^*)} \end{bmatrix} + \lambda D^{l-2} \begin{bmatrix} 2(1+\delta)^{l/2}(l-1)\sigma_r(\hat{X})^2 - 2\frac{(1-\delta)^{l/2}C(l)D^2}{\operatorname{tr}(M^*)} \end{bmatrix}$$
(11)

where $D \coloneqq \| \hat{X} \hat{X}^\top - M^* \|_F$, $C(l) \coloneqq m^{(2-l)/2} \left(\frac{2^l - 1}{l} - 1 \right)$

This can be compared to the lifted technique proposed in [Ma et al., 2023]. The presented method can amplify the negative curvature of those points X that satisfy

$$\|XX^\top - M^*\|_F^2 \geq \frac{1+\delta}{1-\delta}\operatorname{tr}(M^*)\sigma_r^2(\hat{X})$$

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Where in comparison to (10) the multiplicative factor to $\operatorname{tr}(M^*)\sigma_r^2(\hat{X})$ becomes

$$\frac{(1+\delta)+\lambda(l-1)(1+\delta)^{l/2}D^{l-2}}{(1-\delta)/2+\lambda C(l)(1-\delta)^{l/2}D^{l-2}},$$

which is on the order of magnitude of

$$\mathcal{O}\left(l\left(\frac{\sqrt{m}}{2}\right)^l\left(\frac{1+\delta}{1-\delta}\right)^{l/2}\right),$$

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This means that by utilizing a high-order loss, we can recover some of the desirable properties of an over-parametrized technique.

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n	λ	$\lambda_{\min}(\nabla^2 f^l(\hat{X}))$	$\lambda_{\max}(\nabla^2 f^l(\hat{X}))$	$\lambda_{\min}(\nabla^2 f^l(X^*))$	$\lambda_{\max}(\nabla^2 f^l(X^*))$
3	0	1.821	3.642	2.18	4.36
3	0.5	1.779	3.855	2.18	4.36
3	5	1.594	7.422	2.18	4.36
3	50	1.470	55.028	2.18	4.36
5	0	0.429	3.898	0.54	4.72
5	0.5	0.421	4.106	0.54	4.72
5	5	0.385	9.117	0.54	4.72
5	50	0.354	69.816	0.54	4.72
7	0	0.516	3.642	0.72	5.08
7	0.5	0.502	4.122	0.72	5.08
7	5	0.456	10.006	0.72	5.08
7	50	0.433	75.786	0.72	5.08



Figure: The ratio between the largest and smallest eigenvalue of Hessian at the spurious local minimum $\lambda_{\max}/\lambda_{\min}(\nabla^2 f^l(\hat{X}))$ with respect to λ under different size n.



(a) $\lambda = 0$ converges to ground truth (b) $\lambda = 0$ converges to a spurious solution around the ground truth

Figure: The evolution of the objective function and the error between the obtained solution $\hat{X}\hat{X}^T$ and the ground truth M^* during the iterations of the perturbed gradient descent method, with a constant step-size. In both cases, high-order loss functions accelerate the convergence.



Figure: Different rows represents different problems. $\lambda=0$ (left column), $\lambda=0.5$ (middle column), $\lambda=5$ (right column), with x-axis and y-axis as two orthogonal directions from the critical point to the ground truth.

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