

A Hybrid Approximation to the Marginal Likelihood

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15 Second Summary

- ▶ Computing the marginal likelihood is computationally challenging, particularly when the dimension of the parameter space is large.
- ▶ Existing methods [3] are known to be slow and potentially inaccurate when MCMC samples are few in number or non-exact.
- ▶ Our algorithm uses MCMC samples to learn a high probability partition of the parameter space and then forms a deterministic approximation over each of these partitions.

Problem Setup

Given data y , a likelihood function $p(y | u)$ indexed by u from a d -dimensional parameter space \mathcal{U} , and a prior distribution $p(u)$, we can write the marginal likelihood or evidence as,

$$p(y) = \int_{\mathcal{U}} p(y | u) p(u) du.$$

Definitions and Notation

Let γ be a probability density defined on \mathbb{R}^d given by

$$\gamma(u) = \frac{e^{-\Phi(u)} \pi(u)}{\mathcal{Z}}, \quad u \in \mathcal{U} \subseteq \mathbb{R}^d.$$

Typically, $\Phi(\cdot)$ corresponds to a negative log-likelihood function and $\pi(\cdot)$ a prior distribution, so $\gamma(\cdot)$ is the corresponding posterior distribution. The marginal likelihood has the following form,

$$\mathcal{Z} = \int_{\mathcal{U}} e^{-\Psi(u)} du, \quad (1)$$

where $\Psi(u) = \Phi(u) - \log \pi(u)$ is the negative log-posterior.

Our Approach

Generally, we can evaluate Ψ , but are unable to compute the integral in Eq. (1). Provided that we can sample from γ , we propose a two-step approach for solving this problem:

Step 1: Obtain a partition of the parameter space that identifies regions of the posterior that have posterior mass.

Step 2: Approximate Ψ over each of these partition sets

Using these steps together provides a way to approximate \mathcal{Z} by computing a simplified version of the integral over partition sets of the parameter space that have ideally taken into account the assumed non-uniform nature of the posterior distribution.

Method

▶ Step 1: High Probability Partitioning of the Parameter Space

- ▶ Using samples u_j from γ , form $(u_j, \Psi(u_j))$, $1 \leq j \leq J$
- ▶ Using $(u_j, \Psi(u_j))$ as covariate-response pairs as input to a regression tree model, we can a dyadic partition of \mathcal{U}
- ▶ Define the compactification, A , of the parameter space \mathcal{U} to be a bounding box using the range of posterior samples,

$$A = \otimes_l \left[\min \{u_j^{(l)}\}, \max \{u_j^{(l)}\} \right], \quad 1 \leq j \leq J, 1 \leq l \leq d,$$

where $u_j^{(l)}$ is the l th component of u_j .

▶ Step 2: Piecewise Constant Approximation to Ψ

$$\widehat{\Psi}(u) = \sum_{k=1}^K c_k^* \cdot \mathbb{1}_{A_k}(u),$$

where $\mathcal{A} = \{A_1, \dots, A_K\}$ is a partition of A , i.e., $A = \bigcup_{k=1}^K A_k$ and $A_k \cap A_{k'} = \emptyset$ for all $k \neq k'$, and c_k^* is a representative value of Ψ within the partition set A_k .

From step 1, we have rectangular partition sets of the form: $A_k = \prod_{l=1}^d [a_k^{(l)}, b_k^{(l)}]$. This leads to the *Hybrid Approximation*,

$$\int_A e^{-\Psi(u)} du \approx \int_A e^{-\widehat{\Psi}(u)} du = \sum_{k=1}^K e^{-c_k^*} \cdot \mu(A_k).$$

Here, $\mu(B) = \int_B 1 du$ is the d -dimensional volume of a set B .

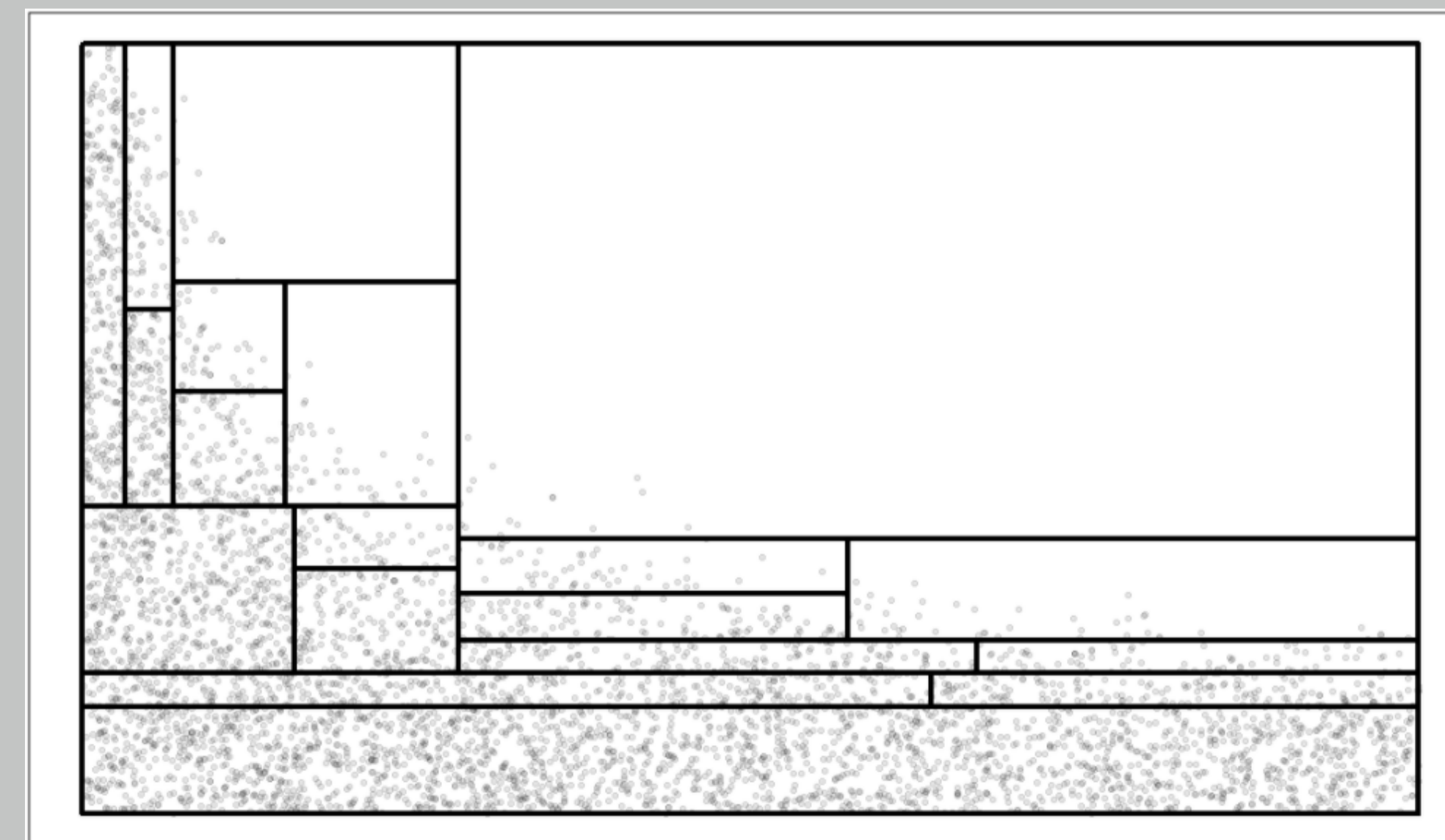


Figure: We draw samples from a density of the form $\gamma(u) \propto \exp(-nu_1^2 u_2^4) \pi(u)$, where $u \in [0, 1]^2$ and $\pi(\cdot)$ is the uniform measure on $[0, 1]^2$. Using these samples as input for CART [1], we form the following partition over the parameter space.

Experiments

▶ Truncated Multivariate Normal Model

- ▶ Linear regression with a truncated multivariate normal (tMVN) prior on β

▶ Unrestricted Covariance Matrices

- ▶ For data $x_1, \dots, x_n \stackrel{iid}{\sim} N_d(0, \Sigma)$, where $\Sigma \in \mathbb{R}^{d \times d}$, we have the following likelihood

$$L(\Sigma) = (2\pi)^{-nd/2} \det(\Sigma)^{-n/2} e^{-\text{tr}(\Sigma^{-1}S)/2},$$

where $S = \sum_{i=1}^n x_i x_i'$. Consider a conjugate inverse-Wishart (IW) prior on Σ , $\mathcal{W}^{-1}(\Lambda, \nu)$.

▶ Gaussian Graphical Models

- ▶ Consider data $x_1, \dots, x_n \stackrel{iid}{\sim} N_d(0, \Omega)$, where Ω is a sparse precision matrix. A probabilistic framework for learning the dependence structure and the graph G requires a prior distribution for (Ω, G) . Conditional on G , we consider the hyper-inverse Wishart (HIW) prior [2] for Ω

▶ Approximate MCMC Samples

- ▶ Linear regression with a multivariate normal-inverse-gamma (MVN-IG) prior on (β, σ^2)
- ▶ We sample from a *mean field approximation* of the posterior distribution

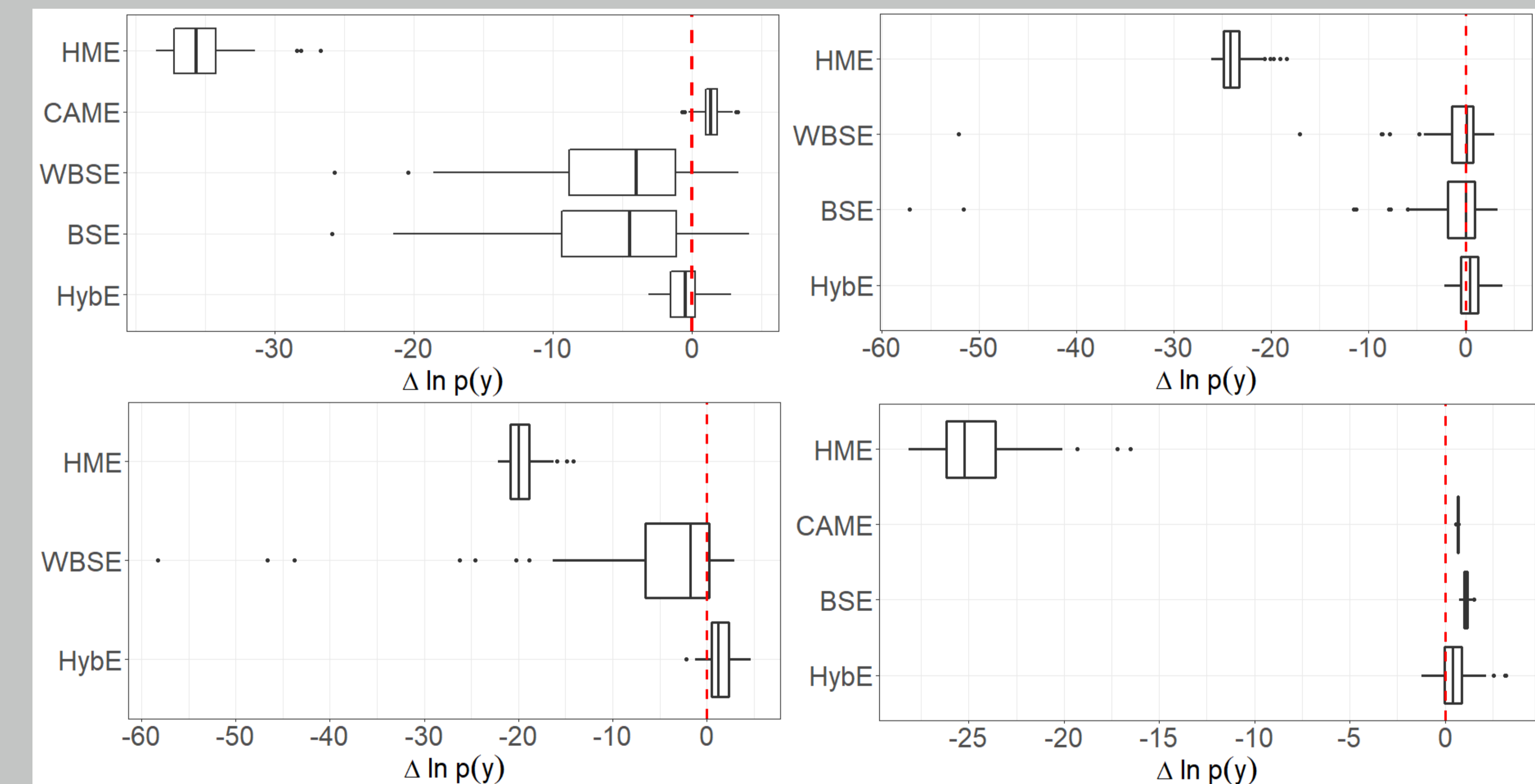


Figure: Boxplots of the error (truth - estimate). For the tMVN example (top left), $\beta \in \mathbb{R}^{20}$. For the IW example (top right), $\Sigma \in \mathbb{R}^{4 \times 4}$, with 10 free parameters. For the HIW example (bottom left), $\Omega \in \mathbb{R}^{5 \times 5}$, with 10 free parameters. For the approximate MVN-IG example (bottom right), $(\beta, \sigma^2) \in \mathbb{R}^{10}$. Other than the Hybrid Estimator (HybE), we considered various competing estimators: Harmonic Mean Estimator (HME), Corrected Arithmetic Mean Estimator (CAME), (Warped) Bridge Sampling Estimator (WBSE, BSE).

References

- [1] L. Breiman, "Classification and regression trees," 1984.
- [2] A. P. Dawid and S. L. Lauritzen, "Hyper markov laws in the statistical analysis of decomposable graphical models," *The Annals of Statistics*, pp. 1272-1317, 1993.
- [3] N. Friel and J. Wyse, "Estimating the evidence - a review," *Statistica Neerlandica*, vol. 66, no. 3, p. 288-308, 2012.