

Top- m identification for linear bandits

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Pure exploration in a multi-armed bandit (MAB) setting

K arms associated with stochastic distributions
with means $\mu_1, \mu_2, \dots, \mu_K$

Q: Which is the best
arm reward-wise?

Sampling rule

Samples arm l_t at round t

Learner

Environment

Updates estimations
according to observations

Stopping rule

Observes reward $r_t = \mu_{l_t} + \eta_t$,

η_t i.i.d. zero-mean sub-Gaussian with fixed variance σ^2

Recommendation rule

Answer

Fixed-confidence Top- m identification in a linear setting



Arms $1, 2, \dots, K < +\infty$ with features $x_1, x_2, \dots, x_K \in \mathbb{R}^N$

means $\mu_1 \geq \mu_2 \geq \dots \geq \mu_m > \mu_{m+1} \geq \dots \geq \mu_K \in \mathbb{R}$

(ε, m, δ) -PAC algorithms, $\delta \in (0, 1), \varepsilon \geq 0$

Returns $\hat{\mathcal{S}}_m^t \subseteq \{1, \dots, K\} = [K]$ of size m at round t such that

$$\mathbb{P}(\hat{\mathcal{S}}_m^t \subseteq \mathcal{S}_m^{*\varepsilon}) \geq 1 - \delta \text{ (error less than } \delta)$$

where $\mathcal{S}_m^{*\varepsilon} \triangleq \{a \in [K] : \mu_a \geq \max_{b \in [K]} \mu_b - \varepsilon\}$ and $\exists \theta \in \mathbb{R}^N, \forall a \in [K], \mu_a = \theta^\top x_a$

- Prior work in a featureless setting (LUCB¹, UGapE²)
- Prior work in a linear setting for $m=1$ ³

¹Kalyanakrishnan, S., Tewari, A., Auer, P., & Stone, P. (2012). *ICML*.

²Gabillon, V., Ghavamzadeh, M., & Lazaric, A. (2012). *NIPS*.

³Soare, M., Lazaric, A., & Munos, R. (2014). *NIPS*; Xu, L., Honda, J., & Sugiyama, M. (2018). *AISTATS*.

GIFA (Gap-Index Focused Algorithms) family for Top- m



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1:  $t \leftarrow 1$ 
2: while  $\text{stopping}(t) > \varepsilon$  do
3:   // estimated  $m$  best arms at  $t$ 
4:    $J(t) \leftarrow \text{compute\_Jt}(t)$ 
5:   // estimated  $m$ -best arm at  $t$ 
6:    $b_t \leftarrow \text{compute\_bt}(t)$ 
7:   // challenger to  $b_t$  at  $t$ 
8:    $c_t \leftarrow \arg \max_{a \notin J(t)} B_{a,b_t}(t)$ 
9:   // sampling arms
10:   $I_t \leftarrow \text{selection}(b_t, c_t)$ 
11:   $r_t \leftarrow \text{sample}(I_t)$ 
12:  Update gap indices  $B_{i,j}(t+1)$ 
13:   $t \leftarrow t + 1$ 
14: end while
15:  $\hat{S}_m^t \leftarrow J(t)$ 
16: return  $\hat{S}_m^t$ 

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Rely on *good gap indices* $B_{i,j}(t)$

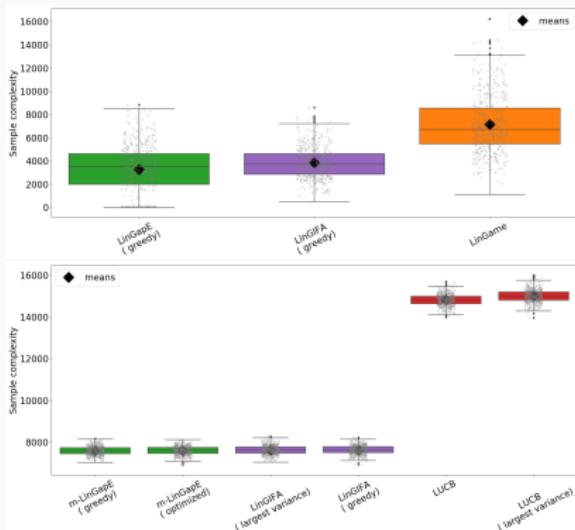
$$\mathbb{P}(\mathcal{E}_m) \geq 1 - \delta$$

$$\mathcal{E}_m \triangleq \bigcap_{t>0} \bigcap_{j \in (\mathcal{S}_m^{*\varepsilon})^c} \bigcap_{k \in \mathcal{S}_m^{*0}} (B_{k,j}(t) \geq \mu_k - \mu_j)$$

Core idea:

1. estimate the best set $J(t)$ at each time t
2. refine it by comparing two ambiguous arms $b_t \in J(t)$ and $c_t \notin J(t)$

Comparison to the state-of-the-art



Still performant in $m = 1$ instance w.r.t. LinGame^a

In drug repurposing instance ($m = 5$), improvement by a factor $\frac{1}{2}$ w.r.t. LUCB^b

^aDegenne, R., Ménard, P., Shang, X., & Valko, M. (2020). *ICML*.

^bKalyanakrishnan, S., Tewari, A., Auer, P., & Stone, P. (2012). *ICML*.

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